



# Models and data

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# INRIA Grenoble - Rhône-Alpes and IBIS



- IBIS: systems biology group at INRIA/Université Joseph Fourier/CNRS
  - Analysis of bacterial regulatory networks by means of models and experiments
  - Biologists, computer scientists, mathematicians, physicists, ...

<http://team.inria.fr/ibis>

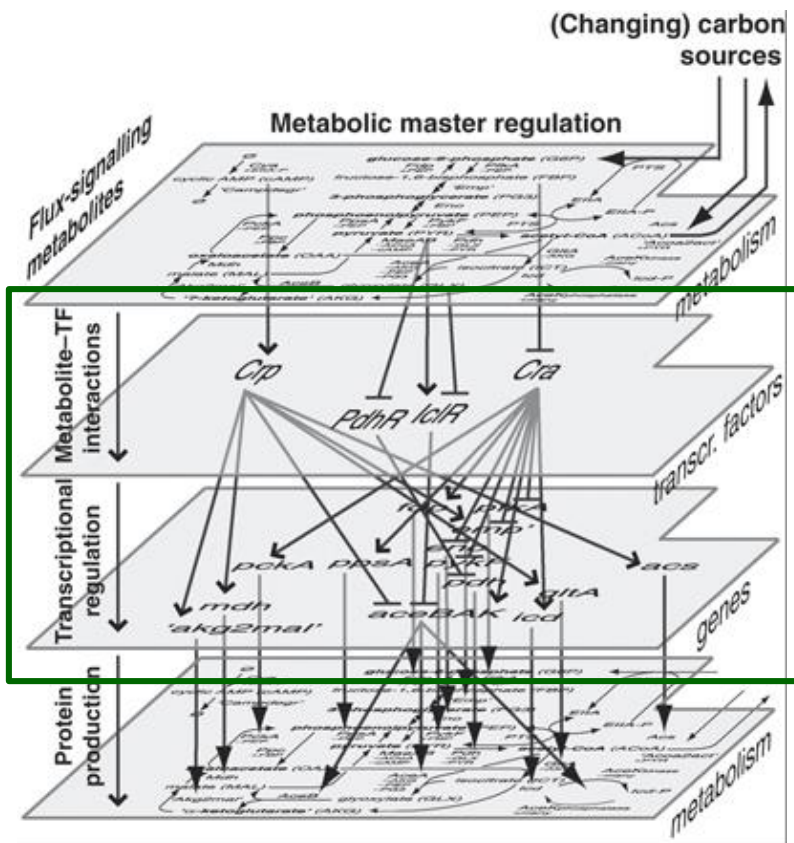


# Overview

- Part 1. Systems biology and kinetic modeling
- Part 2. Metabolic network modeling
- Part 3. Gene regulatory network modeling
  - Quantitative modeling of gene regulatory networks
  - Qualitative modeling of gene regulatory networks
  - Stochastic modeling of gene regulatory networks
  - Practical on integrated models of bacterial growth (Matlab)
- **Part 4. Models and data**

# Gene regulatory networks

- Gene regulatory networks control changes in gene expression levels in response to environmental perturbations



- Gene regulatory networks consist of genes, gene products, signalling metabolites, and their mutual regulatory interactions

Global regulators of transcription involved in glucose-acetate diauxie in *E. coli*

Kotte et al. (2010), *Mol. Syst. Biol.*, 6:355

# Modeling of gene regulatory networks

- Well-established theory for modeling of gene regulatory networks using ordinary differential equation (ODE) models

Bolouri (2008), *Computational Modeling of Gene Regulatory Networks*, Imperial College Press

Polynikis et al. (2009), *J. Theor. Biol.*, 261(4):511-30

- Practical problems encountered by modelers:
  - Knowledge on molecular mechanisms rare
  - **Quantitative information on kinetic parameters and molecular concentrations absent**
  - Large models

# Lack of quantitative information: strategies

- Three main strategies to deal with lack of quantitative data:
  - Test of parameter sensitivity
  - Model reduction and simplification
  - Parameter estimation from time-series data

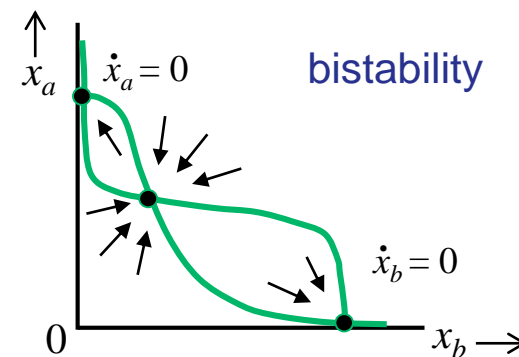
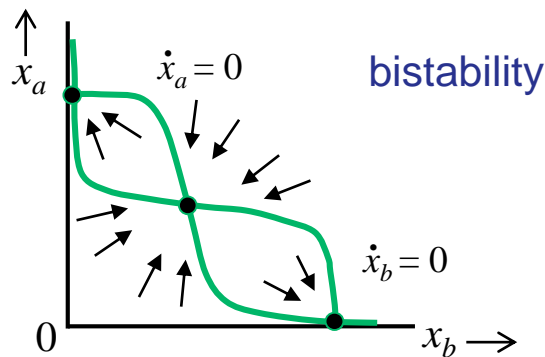
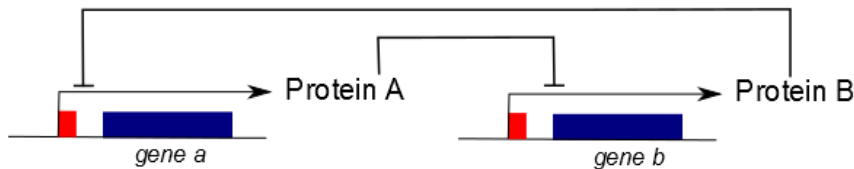
De Jong and Ropers (2006), *Brief. Bioinform.*, 7(4):354-363

# Test of parameter sensitivity

- Important dynamic properties are expected to be **robust** over large ranges of parameter values

Important dynamic properties should be insensitive to moderate variations in parameter values

Stelling *et al.* (2004), *Cell*, 118(6):675-685



# Test of parameter sensitivity

- Important dynamic properties are expected to be **robust** over large ranges of parameter values

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Stelling *et al.* (2004), *Cell*, 118(6):675-685

- Large variety of techniques for assessing sensitivity of models to changes in parameter values

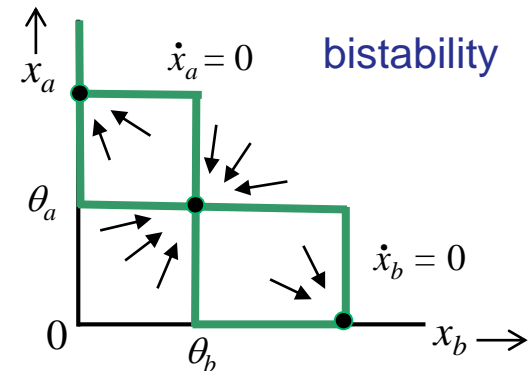
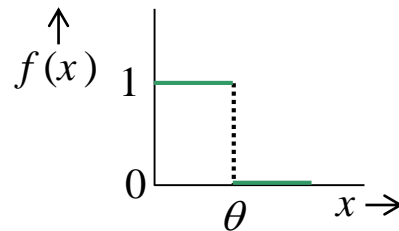
Saltelli *et al.* (2008), *Global Sensitivity Analysis: The Primer*. John Wiley & Sons.



# Model reduction and simplification

- Use model reduction and simplification to obtain models that can be analyzed with less information on parameter values
  - Piecewise-linear instead of nonlinear models
  - Also: Boolean models

$$\begin{aligned}\dot{x}_a &= \kappa_a f(x_b) - \gamma_a x_a \\ \dot{x}_b &= \kappa_b f(x_a) - \gamma_b x_b\end{aligned}$$



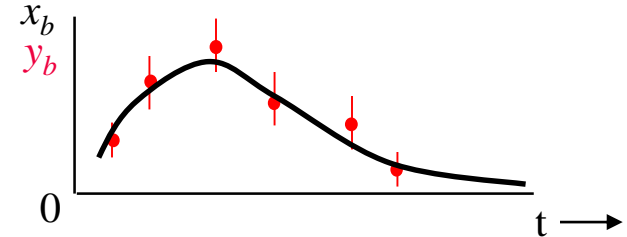
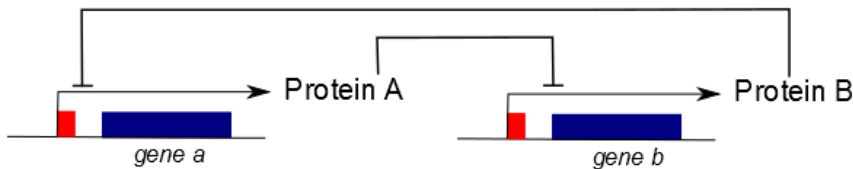
Glass and Kauffman (1973), *J. Theor. Biol.*, 39(1):103-29  
de Jong et al. (2004), *Bull. Math. Biol.*, 66(2):301-40

# Parameter estimation

- **Estimate** parameter values from experimental time-series data  
**Systems identification** in control and engineering

Walter and Pronzato (1997), *Identification of Parametric Models*, Springer

- Given model structure, search parameter values for which model predictions best fit experimental data



- Minimization of objective function, for instance sum of squared errors:

$$\sum_t (x(t, \theta) - y(t))^2$$

# Parameter estimation problem

- Differential algebraic equation (DEA) models

$$\mathbf{A} \frac{d}{dt} \mathbf{x}(t, \mathbf{p}) = \mathbf{f}(\mathbf{x}(t, \mathbf{p}), \mathbf{u}(t), \mathbf{p}), \quad t_0 \leq t \leq t_e$$
$$\mathbf{x}(t_0, \mathbf{p}) = \mathbf{x}_0$$

- Selection matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$
- State variables  $\mathbf{x} : \mathbb{R} \times \mathbb{R}^m \rightarrow \mathbb{R}^n$
- Input variables  $\mathbf{u} : \mathbb{R} \rightarrow \mathbb{R}^l$
- Parameters  $\mathbf{p} \in \mathbb{R}^m$
- Rate functions  $\mathbf{f} : \mathbb{R}^n \times \mathbb{R}^l \times \mathbb{R}^m \rightarrow \mathbb{R}^n$

Ashyraliyev et al. (2009), *FEBS J*, 276(4):886–902

# Parameter estimation problem

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$$\mathbf{x}(t_0, \mathbf{p}) = \mathbf{x}_0$$

- Observables:  $\mathbf{g}(\mathbf{x}(t, \mathbf{p}), \mathbf{u}(t), \mathbf{p})$

$$\mathbf{g} : \mathbb{R}^n \times \mathbb{R}^l \times \mathbb{R}^m \rightarrow \mathbb{R}^q$$

- (Non)linear constraints:  $\mathbf{c}(\mathbf{x}(t, \mathbf{p}), \mathbf{u}(t), \mathbf{p}) \geq 0$

# Parameter estimation problem

- Model predictions at time  $t_i$

$$\mathbf{g}^i = \mathbf{g}(\mathbf{x}(t_i, \mathbf{p}), \mathbf{u}(t_i), \mathbf{p})$$

- Measurements of observables at time  $t_i$

$$y_j \sim \mathcal{F}(\mu_j, \sigma_j)$$

$$\mathbf{y}^i = \mathbf{y}(t_i)$$

- Model discrepancies

$$\mathbf{G} = [\mathbf{g}^1, \dots, \mathbf{g}^N]$$

$$\mathbf{Y} = [\mathbf{y}^1, \dots, \mathbf{y}^N]$$

$$\mathbf{E}(\mathbf{p}) = | \mathbf{G} - \mathbf{Y} |$$

# Parameter estimation problem

- Objective function
  - Weighted sum of squared residuals

$$V(\mathbf{p}) = \sum_{i=1}^N \sum_{j=1}^q \frac{(g_j^i - y_j^i)^2}{(\sigma_j^i)^2} = \mathbf{E}(\mathbf{p})^T \mathbf{W} \mathbf{E}(\mathbf{p})$$

- Other objective functions possible, more adapted to other measurement models or practical considerations!
- **Parameter estimation problem:**

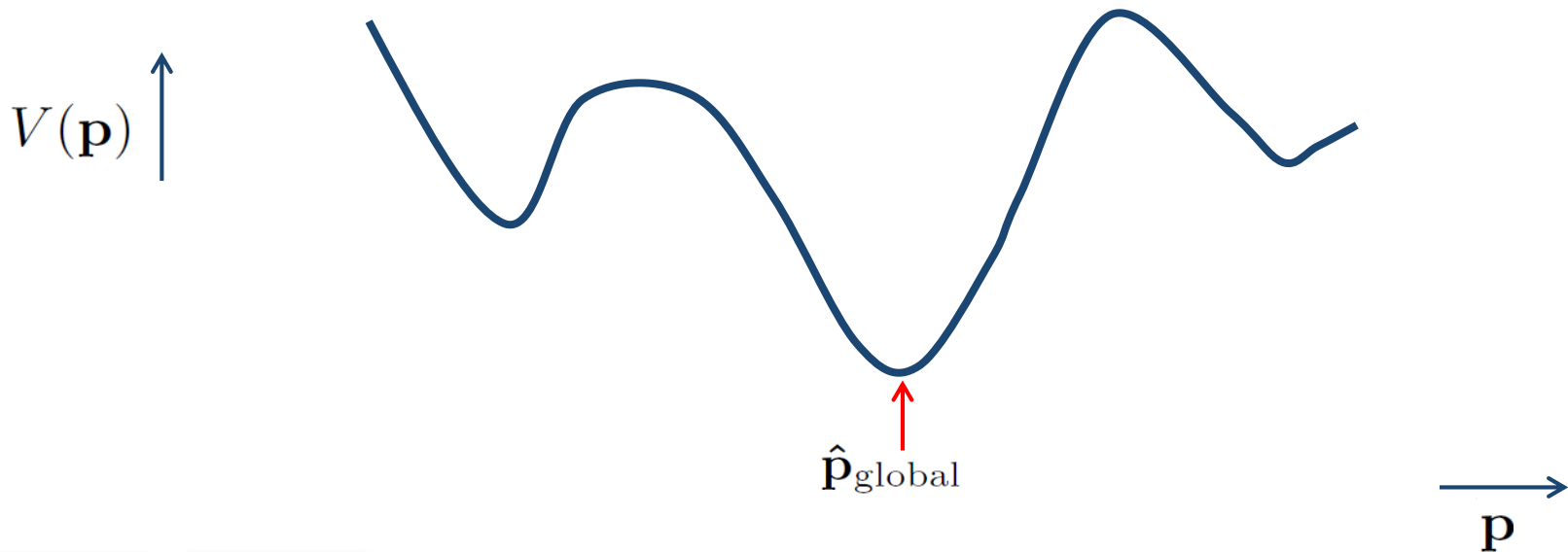
$$\hat{\mathbf{p}} = \arg \min_{\mathbf{p}} V(\mathbf{p})$$

# Parameter estimation methods

- Parameter estimation is a complex optimization problem
- Methods for solving optimization problem:
  - **Global methods:**

$$\hat{\mathbf{p}}_{\text{global}} = \arg \min_{\mathbf{p}} V(\mathbf{p})$$

for all  $\mathbf{p}$  in parameter space

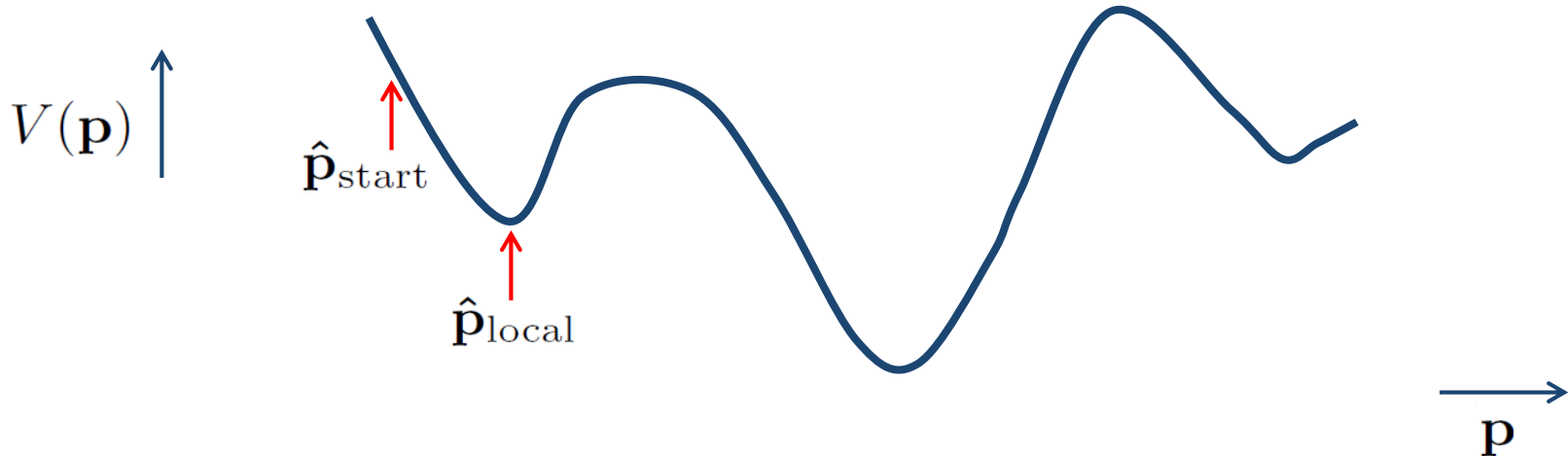


# Parameter estimation methods

- Parameter estimation is a complex optimization problem
- Methods for solving optimization problem:
  - Global methods:
  - **Local methods:**

$$\hat{\mathbf{p}}_{\text{local}} = \arg \min_{\mathbf{p}} V(\mathbf{p})$$

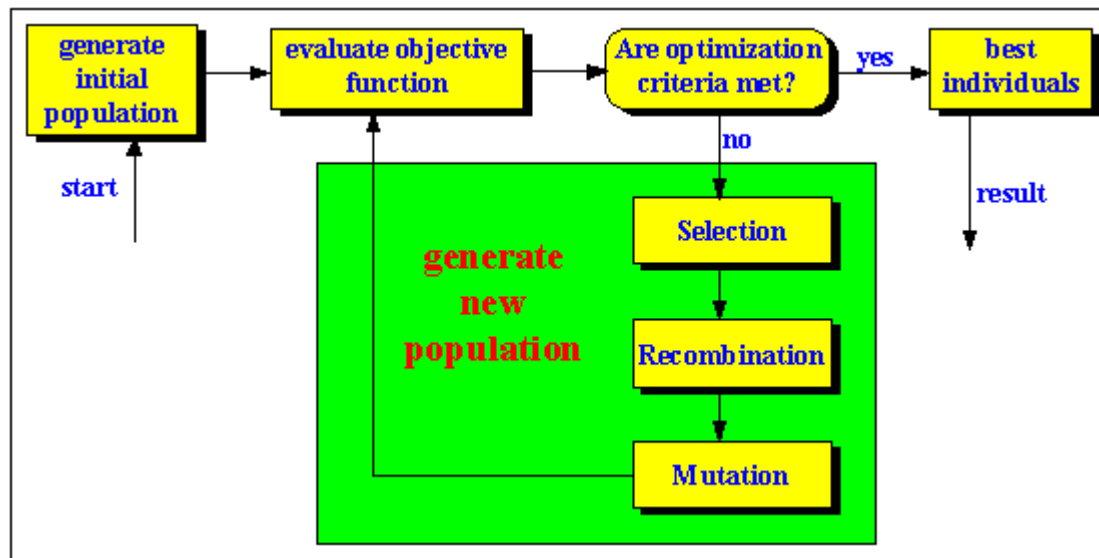
for all  $\mathbf{p}$  in a neighborhood of  $\hat{\mathbf{p}}_{\text{start}}$





# Global optimization methods

- Variety of global optimization methods:
  - Evolutionary algorithms



Ashyraliyev et al. (2009), *FEBS J*, 276(4):886–902

# Global optimization methods

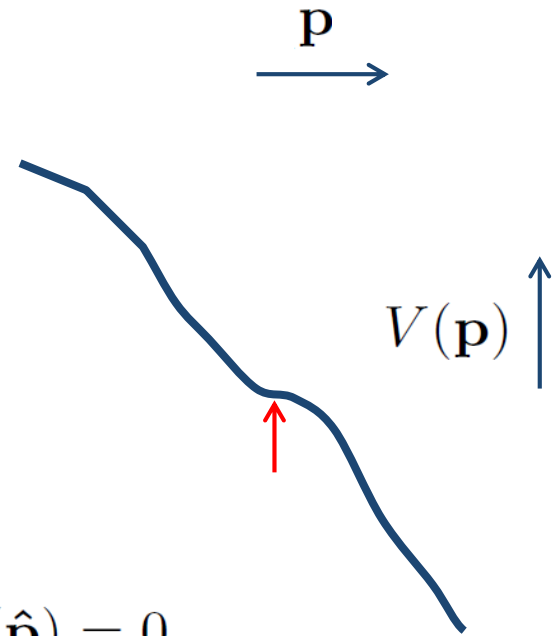
- Variety of global optimization methods:
  - Evolutionary algorithms
  - Simulated annealing
  - ...
- Search of entire parameter space, but generally no convergence proof
- Mostly stochastic algorithms

Ashyraliyev *et al.* (2009), *FEBS J*, 276(4):886–902

# Local optimization methods

- Variety of local optimization methods
  - Gradient methods

Gradient: 
$$\nabla V(\mathbf{p}) = \left[ \frac{\partial}{\partial p_i} V(\mathbf{p}) \right]$$



Necessary condition for local minimum:  $\nabla V(\hat{\mathbf{p}}) = 0$

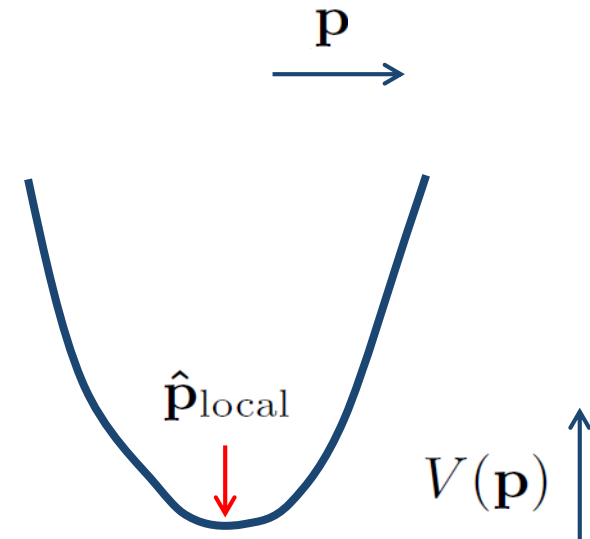
Ashyraliyev *et al.* (2009), *FEBS J*, 276(4):886–902

# Local optimization methods

- Variety of local optimization methods
  - Gradient methods

Gradient:  $\nabla V(\mathbf{p}) = \left[ \frac{\partial}{\partial p_i} V(\mathbf{p}) \right]$

Hessian:  $\nabla^2 V(\mathbf{p}) = \left[ \frac{\partial}{\partial p_i \partial p_j} V(\mathbf{p}) \right]$



Necessary condition for local minimum:  $\nabla V(\hat{\mathbf{p}}) = 0$

Sufficient condition for local minimum:

$$\nabla V(\hat{\mathbf{p}}) = 0 \quad \text{and} \quad \mathbf{p}^T \nabla^2 V(\hat{\mathbf{p}}) \mathbf{p} > 0 \quad \text{for all } \mathbf{p}$$

# Local optimization methods

- Variety of local optimization methods
  - Gradient methods

$$\mathbf{p}_{\text{new}} = \mathbf{p} + \alpha d\mathbf{p}, \quad V(\mathbf{p}_{\text{new}}) < V(\mathbf{p})$$

Steepest descent

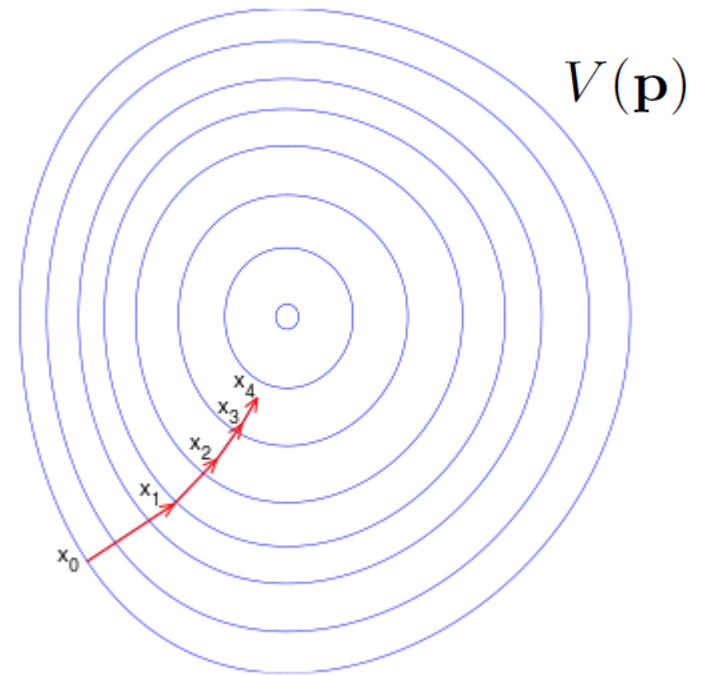
$$d\mathbf{p} = -\nabla V(\mathbf{p})$$

Newton's method

$$d\mathbf{p} = -\nabla^{-2}V(\mathbf{p}) \nabla V(\mathbf{p})$$

Other choices for  $d\mathbf{p}$  :

Adaptive choice of  $\alpha$



# Local optimization methods

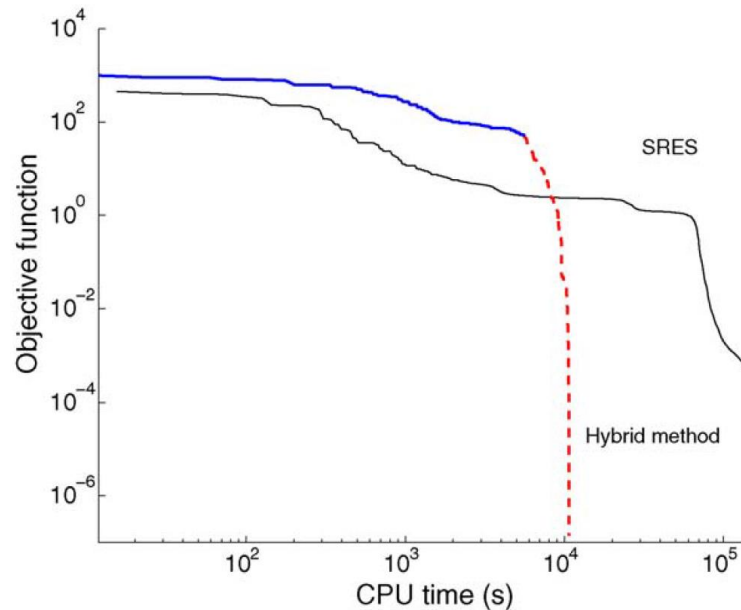
- Variety of local optimization methods
  - Gradient methods
  - Direct search
  - ...
- Local search of parameter space, but proof of (speed of) convergence
- Mostly deterministic algorithms

Ashyraliyev *et al.* (2009), *FEBS J*, 276(4):886–902

# Hybrid optimization method

- **Hybrid optimization:** global followed by local optimization
- In practice, hybrid optimization methods work well on large nonlinear models used in systems biology

Test on benchmark identification problems



Rodriguez-Fernandez *et al.* (2006), *Biosystems*, 83: 248–65

# Constrained optimization methods

- Differential algebraic equation (DEA) models

$$\mathbf{A} \frac{d}{dt} \mathbf{x}(t, \mathbf{p}) = \mathbf{f}(\mathbf{x}(t, \mathbf{p}), \mathbf{u}(t), \mathbf{p}), \quad t_0 \leq t \leq t_e$$
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- (Non)linear constraints:

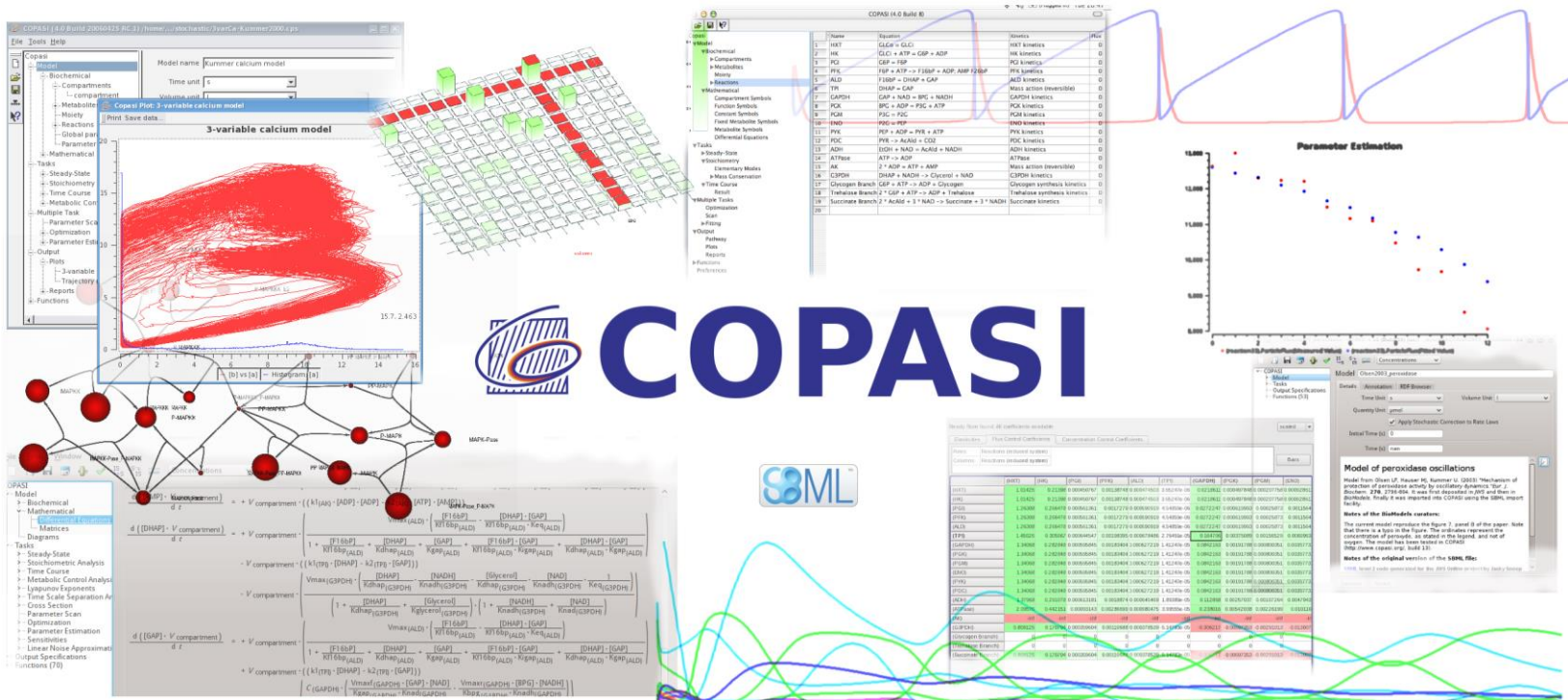
$$\mathbf{c}(\mathbf{x}(t, \mathbf{p}), \mathbf{u}(t), \mathbf{p}) \geq 0$$

- Constraints can be implemented in different ways
  - Penalty term in objective function
  - Search in subspace defined by (in)equality constraints
  - ....



# Parameter estimation tools

- Large number of dedicated parameter estimation tools in systems biology, in addition to general-purpose tools



**COPASI**



Hoops et al. (2006), *Bioinformatics*, 22:3067-74



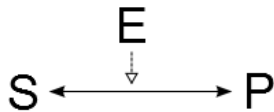
# Multi-scale network of *E. coli* metabolism

- Estimation of model parameters using steady-state data: algebraic equations

Published data sets for balanced growth on either glucose or acetate

$$N \cdot v = 0$$

- **Divide-and-conquer strategy** based on model structure
  1. Estimate reaction rates at steady state
  2. Identify model parameters for individual reactions from reaction rate estimations and measurements of concentrations



$$v(s, p) = \frac{V_m^+ \cdot s / K_{m1} - V_m^- \cdot p / K_{m2}}{1 + s / K_{m1} + p / K_{m2}}$$

Kotte *et al.* (2009), *Bioinformatics*, 25(4):519-25

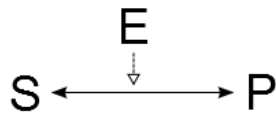
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- **Divide-and-conquer strategy** based on model structure
  1. Estimate reaction rates at steady state
  2. Identify model parameters for individual reactions from reaction rate estimations and measurements of concentrations
  3. Re-estimate integrated model

$$f_{E,Pdh} = \frac{x_{Pdh} p_{Pdh,kcat} \frac{x_{PYR}}{p_{Pdh,K_{PYR}}} \left(1 + \frac{x_{PYR}}{p_{Pdh,K_{PYR}}}\right)^{p_{Pdh,n}-1}}{\left(1 + \frac{x_{PYR}}{p_{Pdh,K_{PYR}}}\right)^{p_{Pdh,n}} + p_{Pdh,L} \left(1 + \frac{x_{GLX}}{p_{Pdh,K_{GLX}}} + \frac{x_{PYR}}{p_{Pdh,K_{I,PYR}}}\right)^{p_{Pdh,n}}}$$

$$f_{E,PfkA} = \frac{x_{PfkA} p_{PfkA,kcat} \frac{x_{G6P}}{p_{PfkA,K_{G6P}}} \left(1 + \frac{x_{G6P}}{p_{PfkA,K_{G6P}}}\right)^{p_{PfkA,n}-1}}{\left(1 + \frac{x_{G6P}}{p_{PfkA,K_{G6P}}}\right)^{p_{PfkA,n}} + p_{PfkA,L} \left(1 + \frac{x_{PEP}}{p_{PfkA,K_{PEP}}}\right)^{p_{PfkA,n}}}$$

Kotte et al. (2010), *Mol. Syst. Biol.*, 6: 355

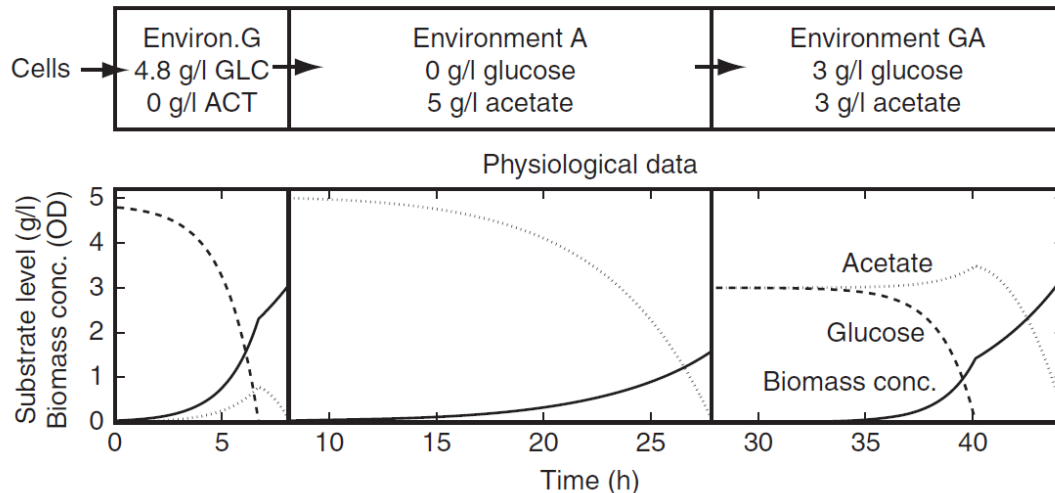
# Multi-scale network of *E. coli* metabolism

- Estimation of model parameters using steady-state data: algebraic equations

Published data sets for balanced growth on either glucose or acetate

$$N \cdot v = 0$$

- Model reproduces known physiological behavior of *E. coli*: diauxic growth and carbon catabolite repression



Kotte *et al.* (2010), *Mol. Syst. Biol.*, 6: 355

# Identifiability analysis

- Parameter  $p_j$  is (globally) **identifiable**, if it can be uniquely determined from given model input  $\mathbf{u}(t)$  and error-free data
- Model is (globally) identifiable, if all of its parameters are
- **A-priori identifiability** analysis
  - Detect structural problems of model

$$\frac{d}{dt}x(t, \mathbf{p}) = p_1 \cdot x + p_2 \cdot x$$

Given measurements of  $x$ , it is not possible to obtain independent estimates of both parameters

Walter and Pronzato (1997), *Identification of Parametric Models*, Springer



# Identifiability analysis

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- Model is (globally) identifiable, if all of its parameters are
- **A-priori identifiability** analysis
  - Detect structural problems of model
- **Practical or a-posteriori identifiability** analysis
  - Problems with precision and quality of data
  - Correlation between variables
- Parameter  $p_j$  is practically identifiable if its confidence interval is of finite size
- Model is practically identifiable, if all of its parameters are



# Identifiability analysis using profile likelihood

- Objective function

$$V(\mathbf{p}) = \sum_{i=1}^N \sum_{j=1}^q \frac{(g_j^i - y_j^i)^2}{(\sigma_j^i)^2} = \mathbf{E}(\mathbf{p})^T \mathbf{W} \mathbf{E}(\mathbf{p})$$

$$y_j \sim \mathcal{N}(\mu_j, \sigma_j) \text{ iid}$$

is proportional to **log-likelihood**

Minimization of  $V(\mathbf{p})$  corresponds to maximum likelihood estimation

- Profile likelihood for parameter  $p_i$  ranging over interval  $p_i = \tilde{p}_i \in [\underline{p}, \bar{p}]$  is defined as

$$V_{PL}(\tilde{p}_i) = \min_{\mathbf{p} \in \mathbb{R}^m, p_i = \tilde{p}_i} V(\mathbf{p})$$

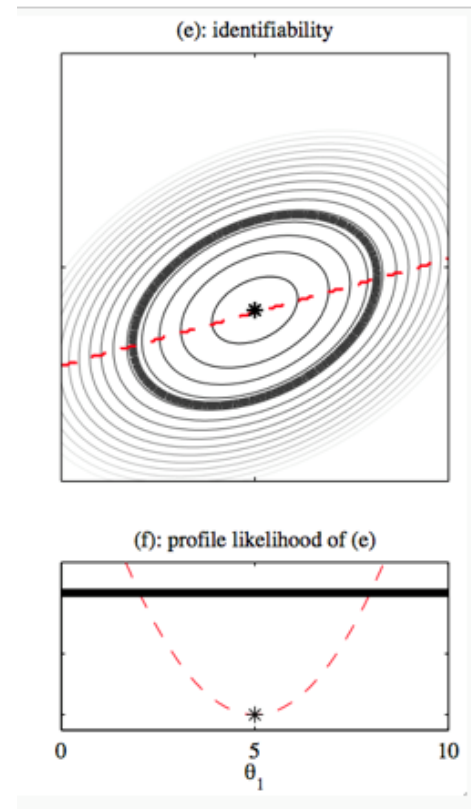
- Likelihood-based confidence interval  $\{\mathbf{p} \mid V(\mathbf{p}) - V(\hat{\mathbf{p}}) < \alpha\}$

Threshold given by distribution

Raue *et al.* (2009), *Bioinformatics*, 25(15):1923-9

# Identifiability analysis using profile likelihood

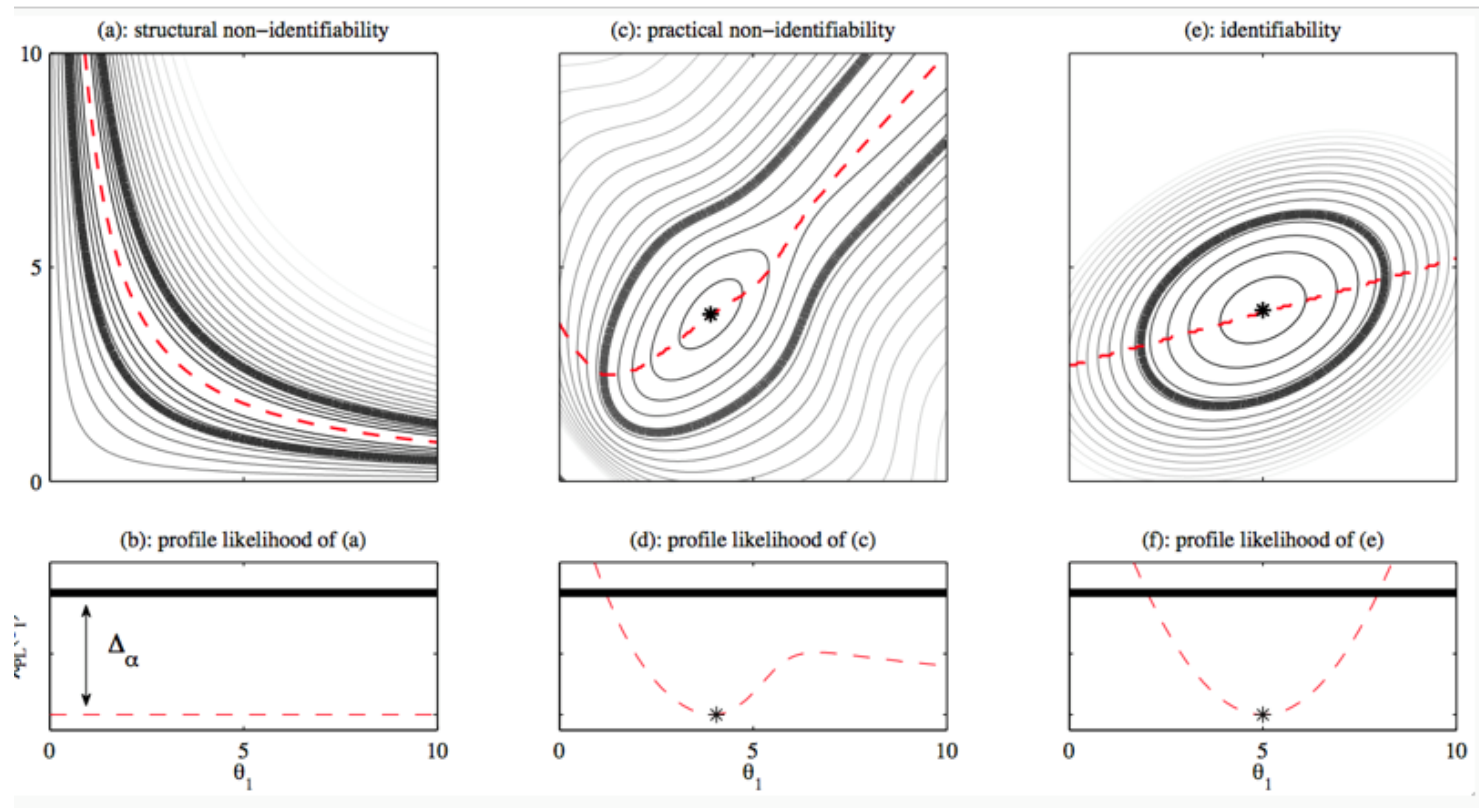
- Intuition: for each parameter, explore the parameter space in direction of least increase of objective function



Raue *et al.* (2011), *IET Syst. Biol.*, 5(2):120-30

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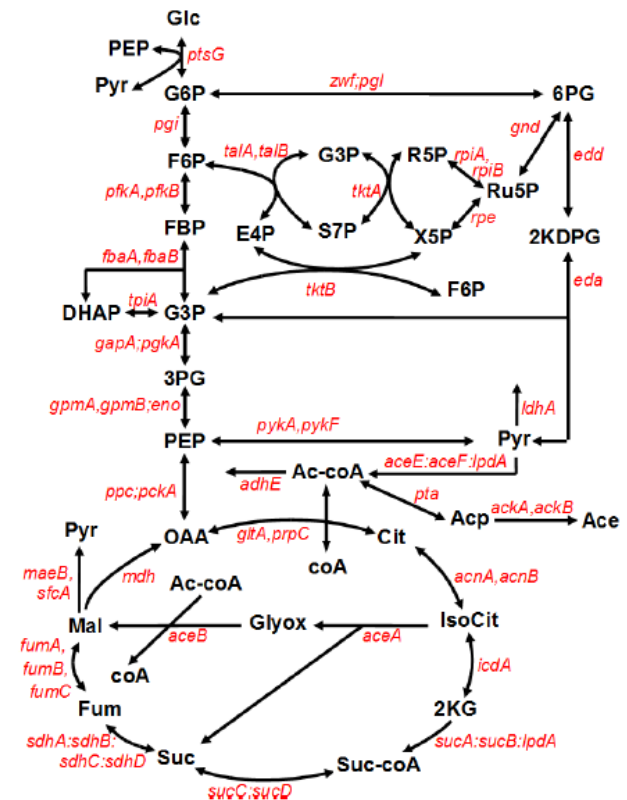
# Identifiability analysis of *E. coli* metabolism

- Simplified model of central carbon metabolism in *E. coli*
- Model at steady state and lin-log kinetics for describing reactions

$$v = \text{diag}(e) \cdot (a + B^x \cdot \ln x + B^u \cdot \ln u)$$

$$N \cdot v = 0$$

- Measurements:
  - Metabolite concentrations  $u, x$
  - Enzyme concentrations  $e$
  - Metabolic fluxes (reaction rates at steady state)  $J$
- Parameters to estimate:  $a \cdot B^x \cdot B^u$



Berthoumieux *et al.* (2011), *Bioinformatics*, 27(13):i186–93



# Identifiability analysis of *E. coli* metabolism

- Simplified model of central carbon metabolism in *E. coli*
- Most parameters are not identifiable as determined from profile likelihood!

Reactions	Metabolites																							
	Glc	PEP	G6P	Pyr	F6P	FBP	DHAP	3PG	AcoA coA	6PG	Ru5P	R5P	S7P	2KG	Suc	Fum	Mal	ATP ADP	Cit	NADPH NADP	NADH NAD	FAD	Ace	
	0.29	-0.89	0.79	1.87	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	0	0	-0.33	0	0.23	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	0	-0.16	0	0	0.04	-0.28	0	0	0	0	0	0	0	0	0	0	0	0.09	0	0	0	0	0	
	0	0	0	0	0	-0.3	0.06	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	0	0	0	0	0	0	-0.07	0.22	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	0	0	0	0	0	-0.18	0	-0.05	0	0	0	0	0	0	0	0	0	0.32	0	0	-0.17	0	0	
	0	0.26	0	0	0	0	0	-0.12	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
	0	0.12	0	0.49	0	-0.19	0	0	0	0	0	0	0	0	0	0	0	0.16	0	0	0	0	0	
	0	0	0	0.64	0	0	0	0.05	0	0	0	0	0	0	0	0	0	0	0	0	-0.21	0	0	
	0	0	-0.22	0	0	0	0	0	-0.24	0	0	0	0	0	0	0	0	0	0	-0.01	0	0	0	
	0	0	0	0	0	0	0	0	0.48	-0.09	0	0	0	0	0	0	0	0	0	-0.01	0	0	0	
	0	0	0	0	0	0	0	0	0	0.46	0	-0.39	0	0	0	0	0	0	0	0	0	0	0	
	0	0	-0.74	0	0	0	0	0	0	0.3	-0.16	0	0	0	0	0	0	0	0	0	0	0	0	
	0	0	0	0	0	0	0	0	0	0	0.01	-0.1	0	0	0	0	0	0	0	0	0	0	0	
	0	0	0	0	-0.32	0	0	0	0	0	0	0.51	0	0	0	0	0	0	0	0	0	0	0	
	0	0	0	0	-0.58	0	0	0	0	0	0.35	0	0	0	0	0	0	0	0	0	0	0	0	
	0	0	0	0	0	0	0	0	0.22	0	0	0	0	-0.001	0	0	0	0	0.49	0	-0.01	0	0	
	0	0	0	0	0	0	0	0	0	0	0	0	0	0.99	0	0	0	0	0.55	0	0	0	0	
	0	0	0	0	0	0	0	0	0.08	0	0	0	0	-0.09	0	0	0	0	0	-0.59	0	0	0	
	0	0	0	0	0	0	0	0	0	0	0	0	0	1.26	0.3	0	0	0	0	0	0	-0.48	0	0
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1.08	-0.44	0	0	0	0	0	0	0.4	0
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.46	0.1	0	0	0	0	0	0	0
	0	0.15	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.01	0	0.31	0	-0.12	0	0	
	0	0.29	0	0	0	-0.13	0	0	0	0	0	0	0	0	0	0	0.1	-1.15	0.21	0	0	0	0	
	0	0	0	-0.31	0	0	0	0	-0.21	0	0	0	0	0	0	0	0.38	0	0	0.36	-0.05	0	0	
	0	0	0	0	0	0	0	0	-0.11	0	0	0	0	0	0.26	0	-0.18	0	0	0	0	0	0	
	0	0.1	-0.09	0.04	-0.06	0	0	0.17	0.1	0	0	0.09	0	-0.01	0	0	0	-0.46	0	-0.003	0.01	0	0	
	0	0	0	-0.03	0	0	0	0	0	0	-0.93	0	0	0	0	0	0	0	0	0	0	0	0	
	0	0	0	-0.06	0	0	0	0	-0.01	0	0	0	0	0	0	0	0	0.21	0	-0.25	-2.03	0	2.19	
	0	0	0	2.67	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.11	0	0	
	0	0	0	0	0	0	0	0	0.91	0	0	0	0	0	0	0	0	0	0	0	0	0	0	

27/31 nonidentifiable reactions

73/100 nonidentifiable parameters

Berthoumieux et al. (2013), *J. Math. Biol.*, 67:1759-1832

# Structural vs parametric identification

- **Parametric identification** assumes model structure given
- **Structural identification** provides joint estimate of model structure and parameters

$$\mathbf{A} \frac{d}{dt} \mathbf{x}(t, \mathbf{p}) = \mathbf{f}(\mathbf{x}(t, \mathbf{p}), \mathbf{u}(t), \mathbf{p}), \quad t_0 \leq t \leq t_e$$
$$\mathbf{x}(t_0, \mathbf{p}) = \mathbf{x}_0$$

- Structural identification very difficult problem, based on exploration of *a-priori* defined model space

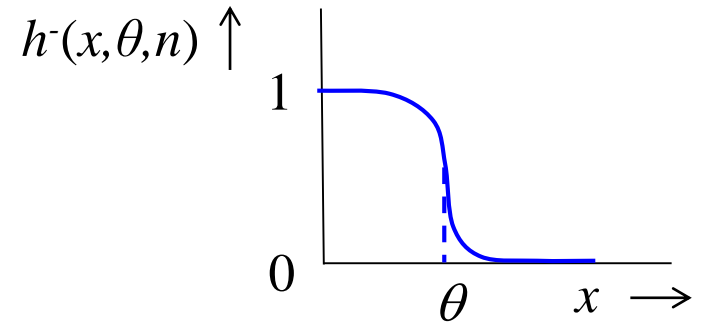
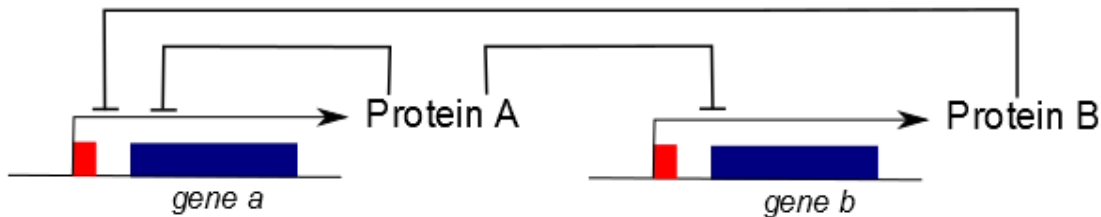


# Structural vs parametric identification

- Method for **structural and parametric identification** of gene regulatory networks from time-series data
  - Exploits monotonicity properties of switch-like regulation functions  $g$  to invalidate interactions

$$\dot{x}_a = \kappa_a h^-(x_a, \theta_{a2}, n) h^-(x_b, \theta_b, n) - \gamma_a x_a$$

$$\dot{x}_b = \kappa_b h^-(x_a, \theta_{a1}, n) - \gamma_b x_b$$



$x$  : protein concentration  
 $\theta$  : threshold concentration  
 $\kappa, \gamma$  : rate constants  
 $n$  : steepness parameter

Porreca et al. (2010), *Bioinformatics*,  
26(9):1239-45



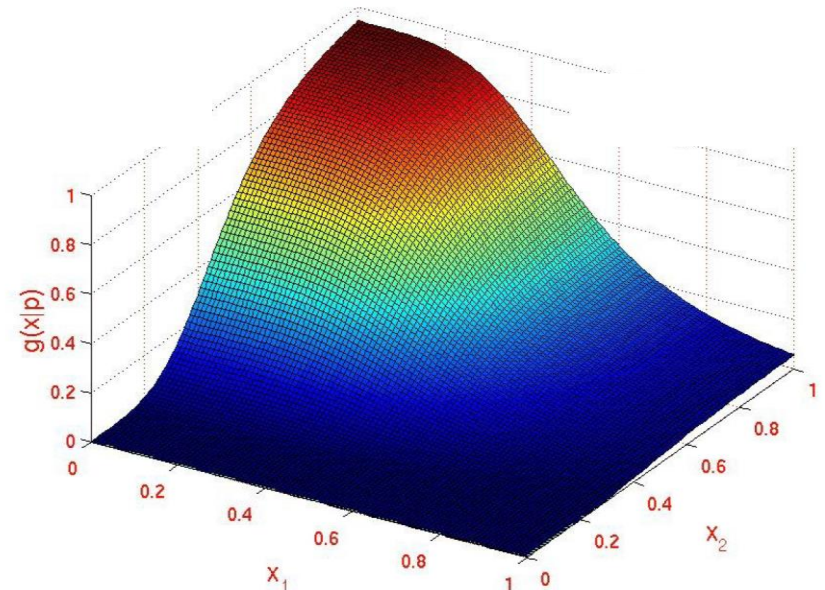
# Structural vs parametric identification

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  - Exploits monotonicity properties of switch-like regulation functions  $g$  to invalidate interactions

Observations  $x_1 \uparrow$ ,  $x_2 \downarrow$  and  $g(x_1, x_2) \uparrow$  rule out pattern  $x_1$  activator and  $x_2$  inhibitor

$$\dot{x}_3 = g(x_1, x_2, p) - \gamma_3 x_3$$

$$g(x_1, x_2, p) \neq \kappa_3 h^+(x_1, \theta_1, n) h^-(x_2, \theta_2, n)$$



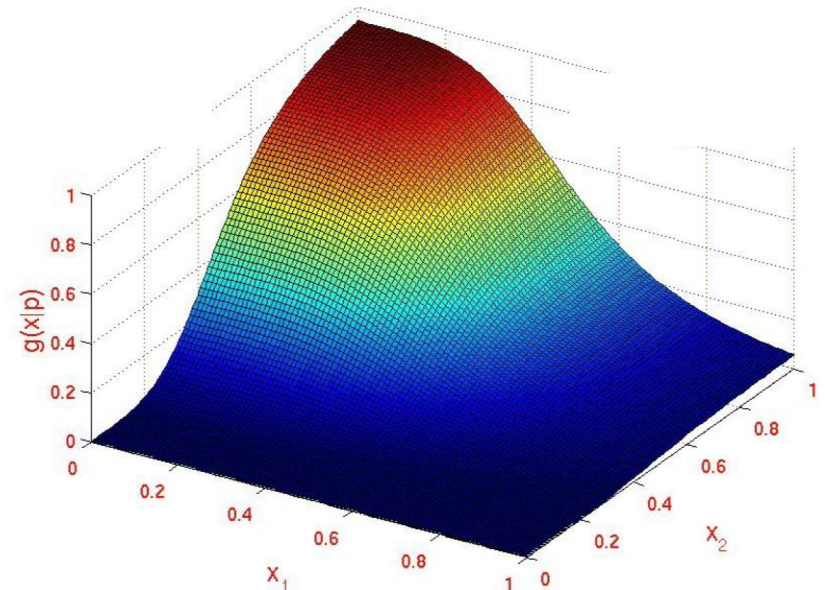
Porreca et al. (2010), *Bioinformatics*,  
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# Structural vs parametric identification

- Method for **structural and parametric identification** of gene regulatory networks from time-series data
  - Exploits monotonicity properties of switch-like regulation functions  $g$  to invalidate interactions
  - Looks for simplest interaction structures consistent with data

Subpatterns of inconsistent patterns  
are also inconsistent

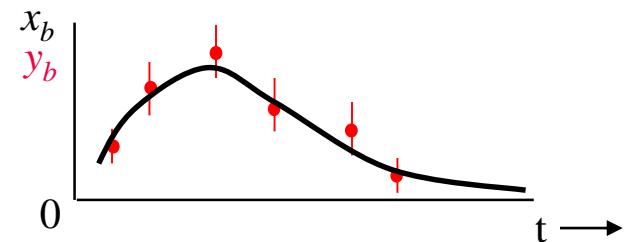
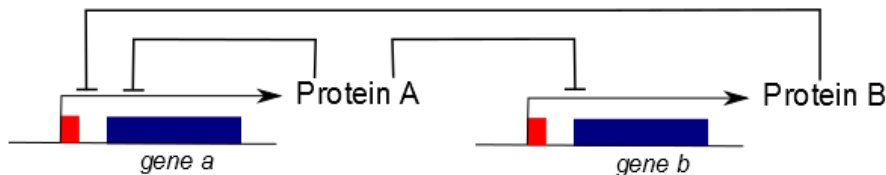
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Porreca *et al.* (2010), *Bioinformatics*,  
26(9):1239-45

# Structural vs parametric identification

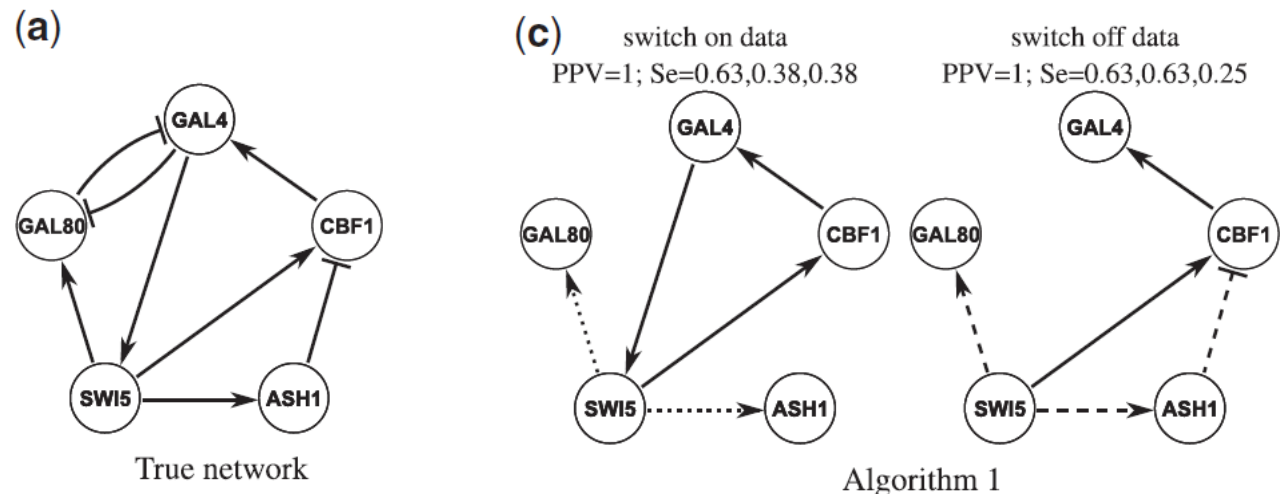
- Method for **structural and parametric identification** of gene regulatory networks from time-series data
  - Exploits monotonicity properties of switch-like regulation functions  $g$  to invalidate interactions
  - Looks for simplest interaction structures consistent with data
  - Estimate parameters for selected interaction structure



Porreca et al. (2010), *Bioinformatics*,  
26(9):1239-45

# Structural vs parametric identification

- Method for **structural and parametric identification** of gene regulatory networks from time-series data
  - Exploits monotonicity properties of switch-like regulation functions  $g$  to invalidate interactions
  - Looks for simplest interaction structures consistent with data
  - Estimate parameters for selected interaction structure
  - Good results on benchmark data set in yeast



Porreca *et al.* (2010), *Bioinformatics*,  
26(9):1239-45

# Structural vs parametric identification

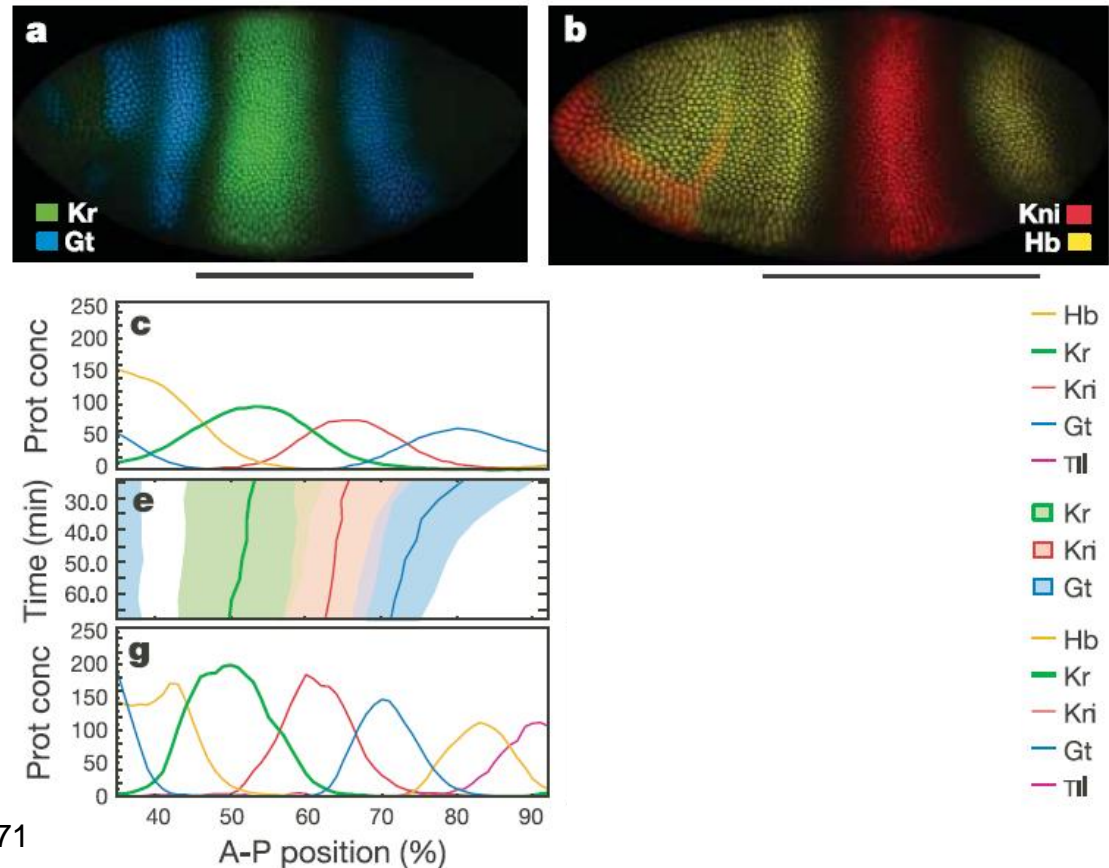
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$$\mathbf{x}(t_0, \mathbf{p}) = \mathbf{x}_0$$

- Structural identification very difficult problem, based on exploration of *a-priori* defined model space
- In certain cases, structural identification reduces to parametric identification

# Parameter estimation from *Drosophila* data

- Measurement of protein concentrations of gap genes during development of *Drosophila* embryo



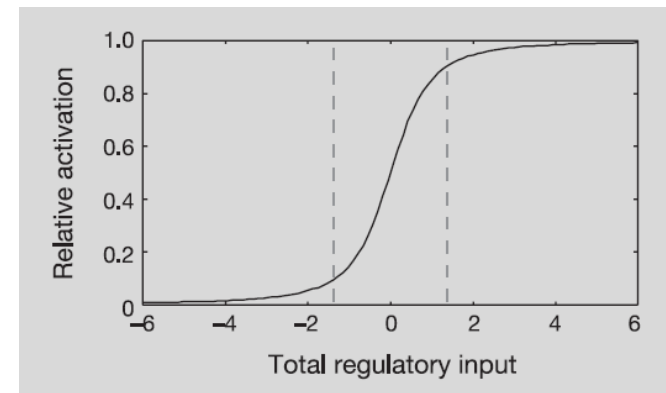
Jaeger et al. (2004), *Nature*, 430(6997):368-71

# Parameter estimation from *Drosophila* data

- Neural-network-like model of connections between gap genes
  - Model with 58 nuclei and 7 variables (proteins) per nucleus
  - Free diffusion of proteins because at early stages of development embryo is syncytium (multinucleate cell)
  - Sigmoidal response functions
  - Connectivity pattern encoded in parameter matrix  $T$ , so parametric **and** structural identification

$$\frac{dv_i^a}{dt} = R_a g(u^a) + D^a [(v_{i-1}^a - v_i^a) + (v_{i+1}^a - v_i^a)] - \lambda_a v_i^a$$

$$u^a = \sum_b T^{ab} v_i^b + m^a v_i^{Bcd} + h^a$$

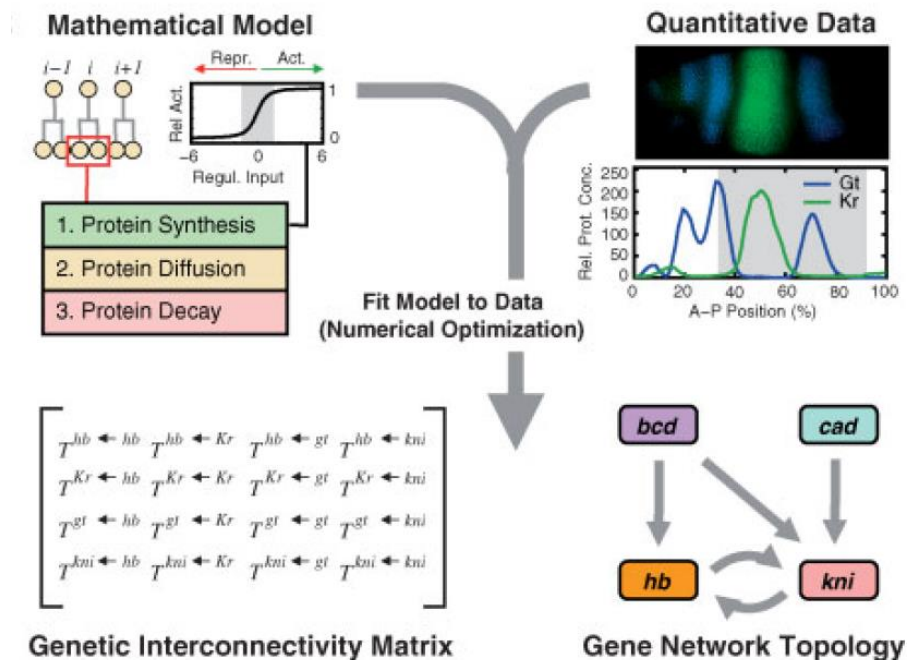


Jaeger et al. (2004), *Nature*, 430(6997):368-71



# Parameter estimation from *Drosophila* data

- Neural-network-like model of connections between gap genes
- Brute-force parameter estimation by fitting model to data  
Parallelized simulated annealing

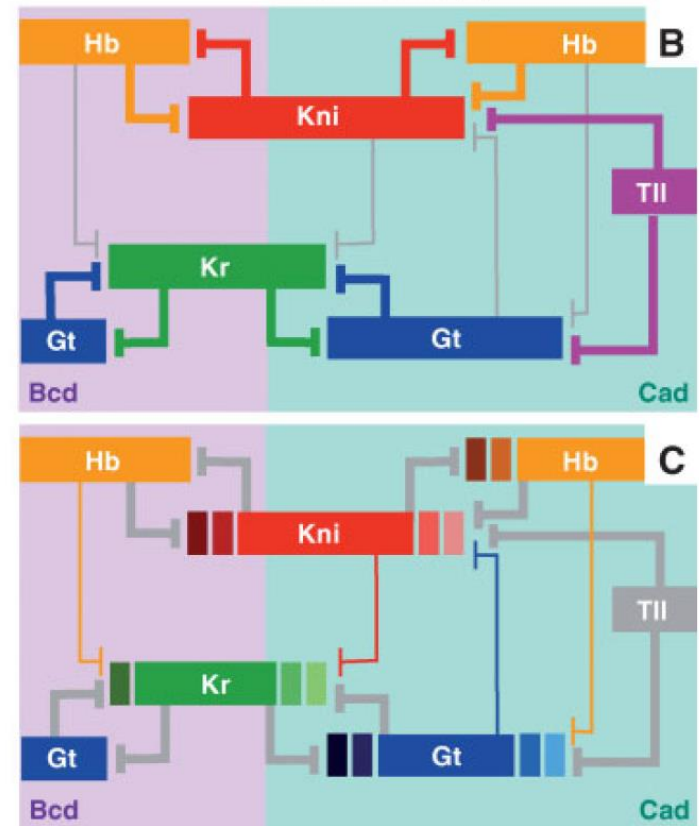
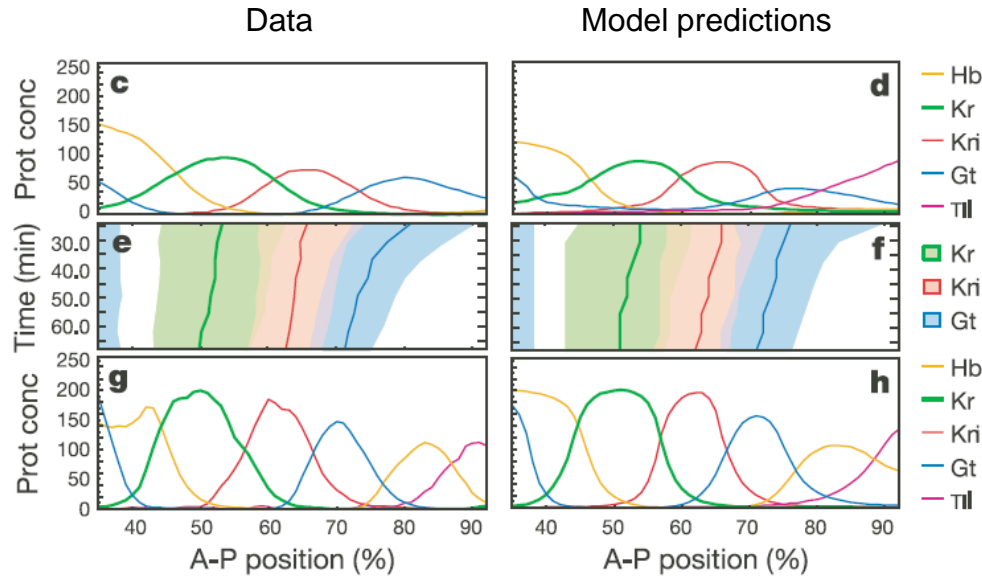


Jaeger and Reinitz (2006), *BioEssays*,  
28(11):1102-11



# Shifts in gap gene domains

- What is function of **cross-inhibition** between gap genes?  
 Model predicts that they are important for shift in gap gene domains after their initial establishment

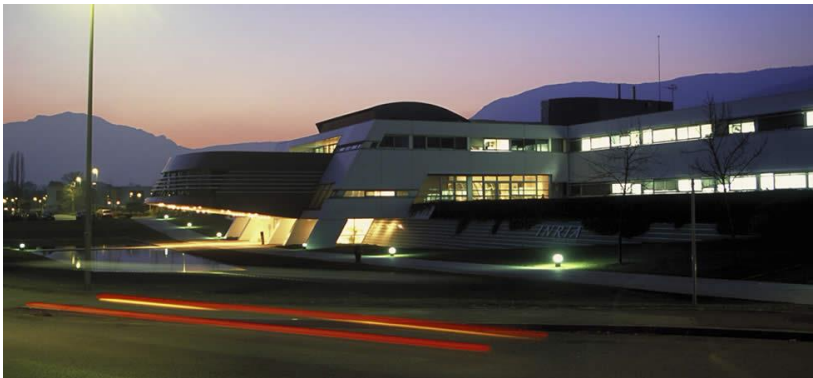


# Conclusions

- Identification of models requires estimation of parameters
  - Optimization problem: minimization of objective function
  - Large variety of methods available: global vs local, deterministic vs stochastic, ...
- Identifiability issues: structural and practical identifiability
- Structural vs parametric identification
- Other issues: optimal experimental design, ensemble models
- Large-scale parameter estimation problems in systems biology are very difficult to solve
  - Clever tricks
  - Model-dependent heuristics
  - Model reduction, ...

# Internships in IBIS

- Challenging problems for biologists, physicists, computer scientists, mathematicians, ...
- ... in a multidisciplinary working environment
- Contact: [Hidde.de-Jong@inria.fr](mailto:Hidde.de-Jong@inria.fr) and [ibis.inrialpes.fr](http://ibis.inrialpes.fr)



Courtesy Guillaume Baptist (2008)

**Merci !**



[team.inria.fr/ibis](http://team.inria.fr/ibis)